

# Paper data assimilation with 2D DFT based Kalman filter

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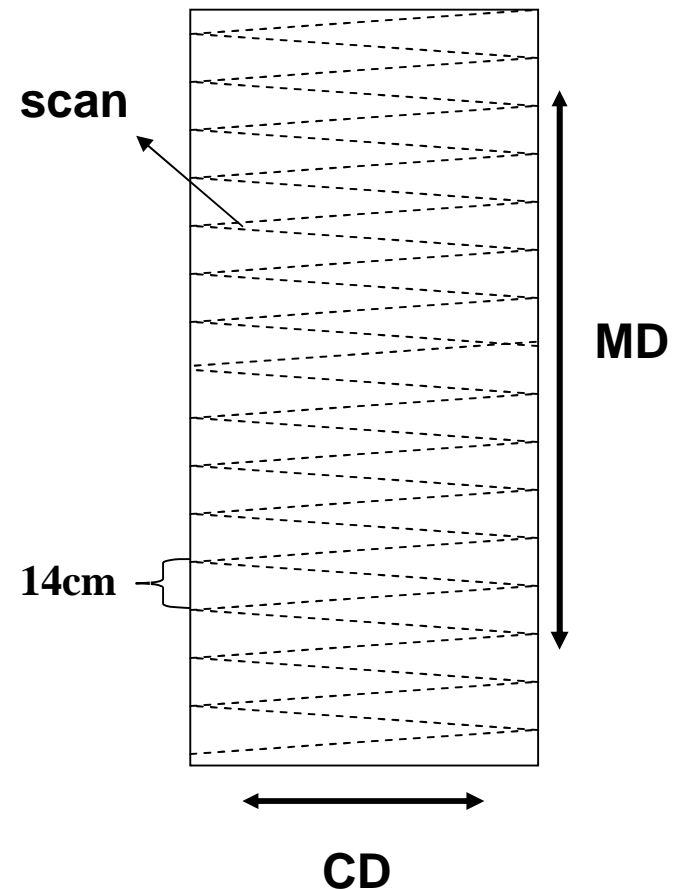
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# Contents

- Details of the dataset we are assimilating
- Idea of 2D discrete Fourier transform
- 2D DFT based Kalman filter on data assimilation

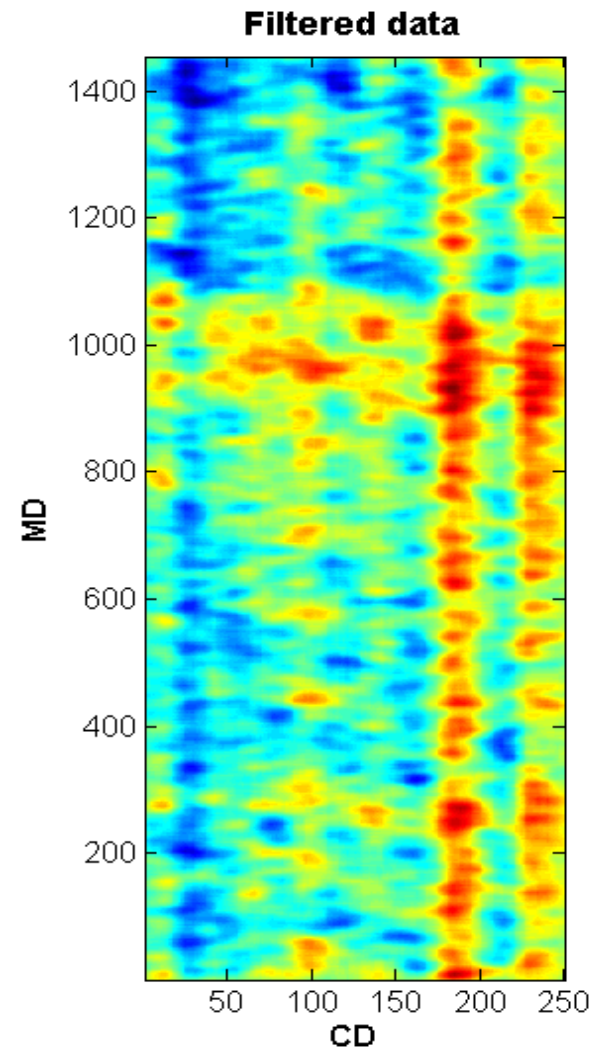
# Basis weight sample dataset

- 2,5m \* 200m paper web
- Measured by special ATPA machine with very tight traversing path
- Each scan equals 14cm in MD and 1cm in CD
- Size of the datamatrix is thus 250\*1454 units

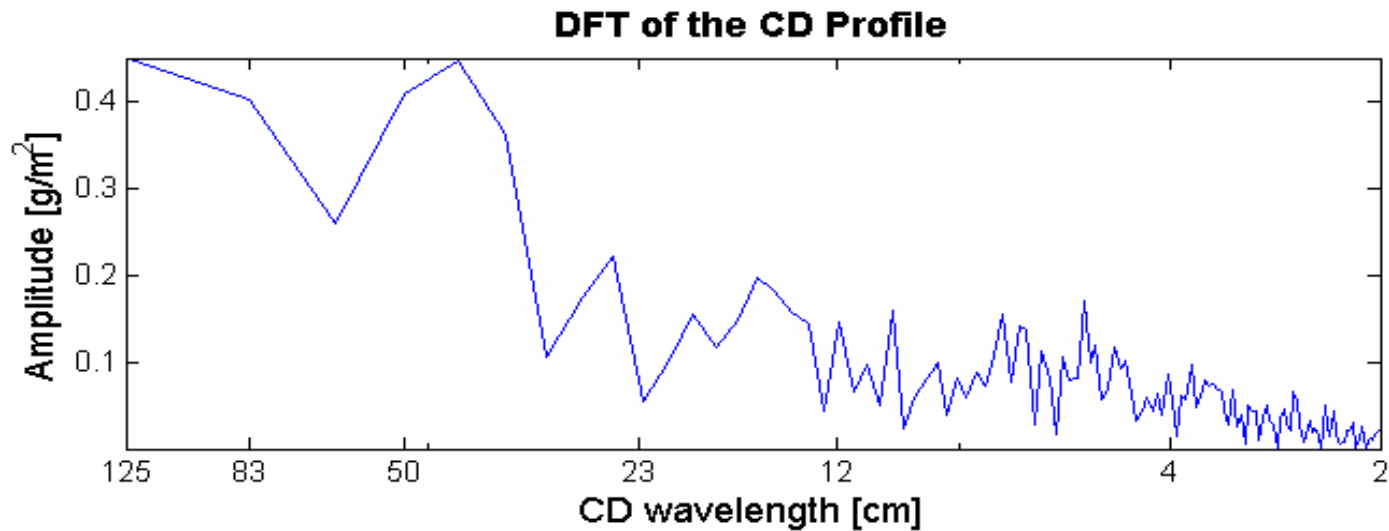
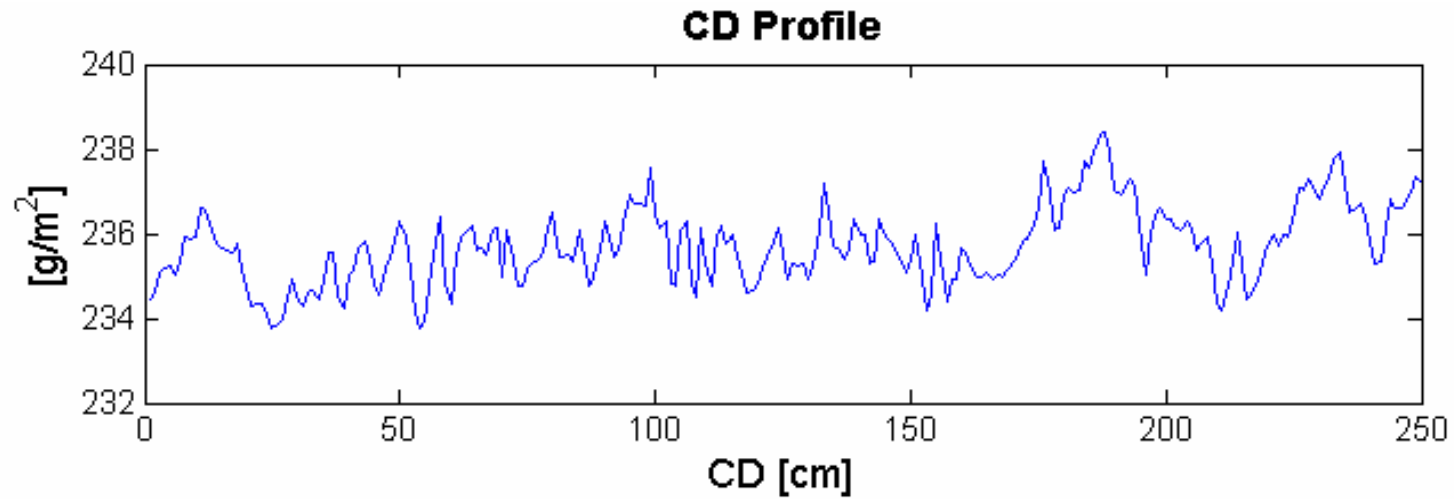


# Figure of filtered dataset

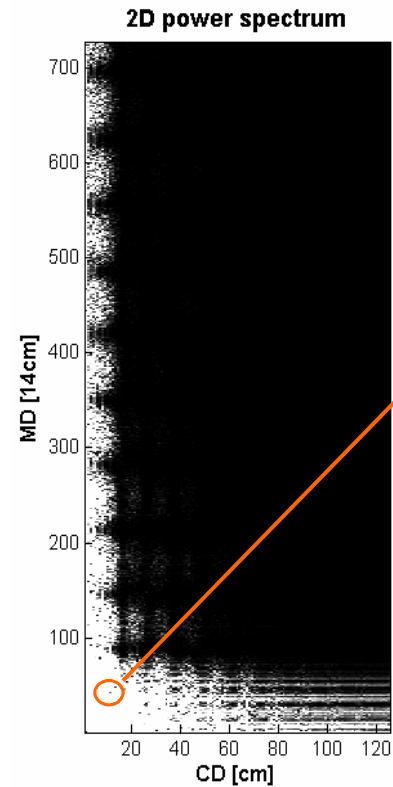
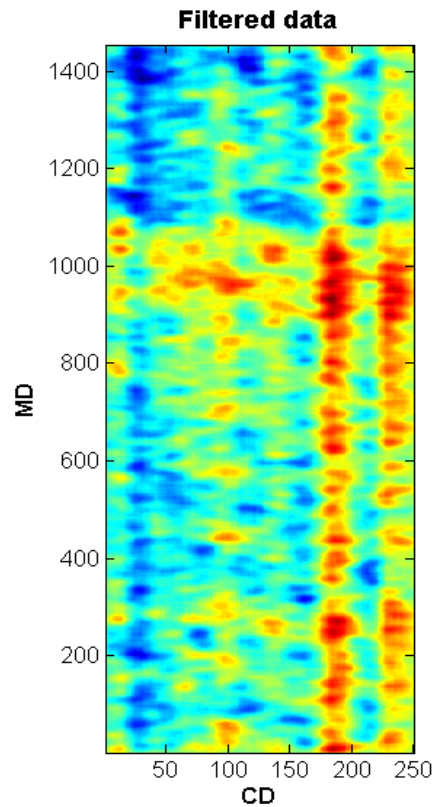
- Half of the real width of a paper roll
- Strong variation can be seen in CD
- Also some MD variation visible



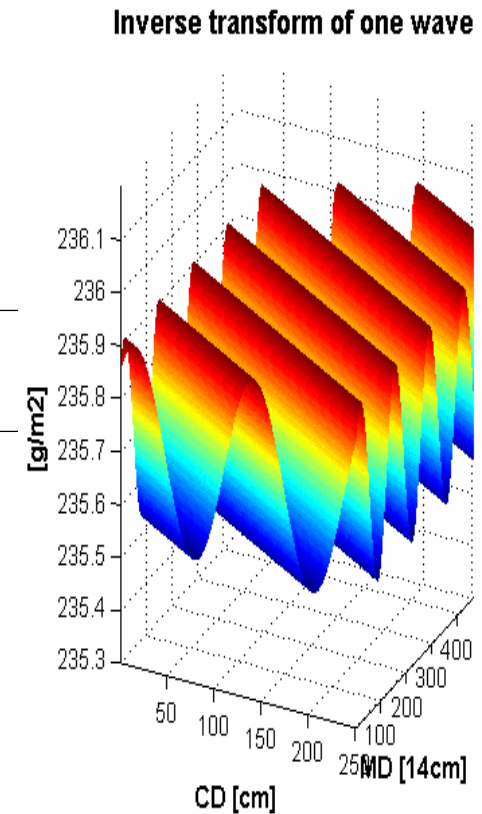
# DFT (Discrete Fourier Transform)



# 2D DFT

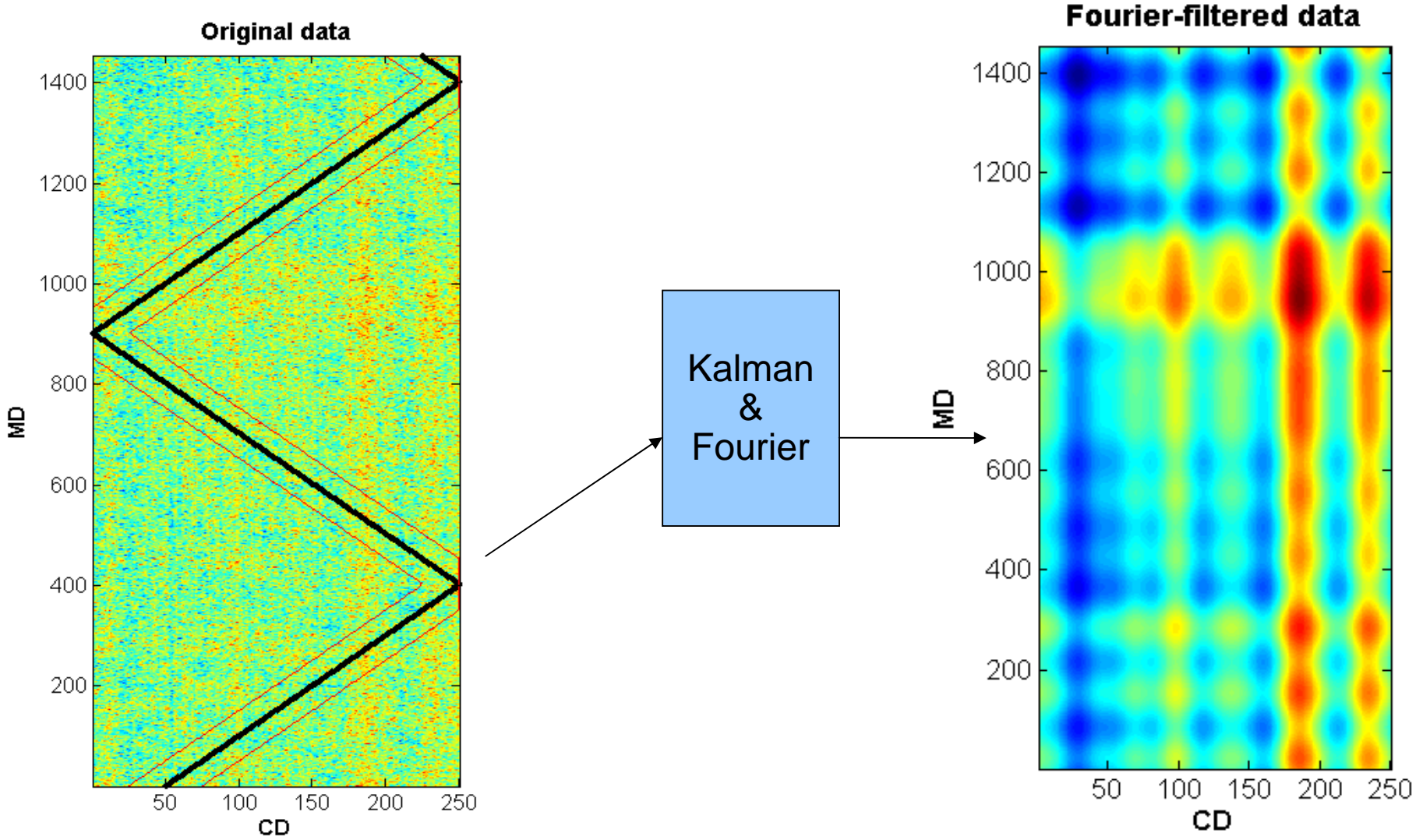


Inverse  
2D DFT



- **With 2D DFT, also diagonal waves can be taken into account, (in addition to CD and MD waves)**

# Basic idea of data assimilation



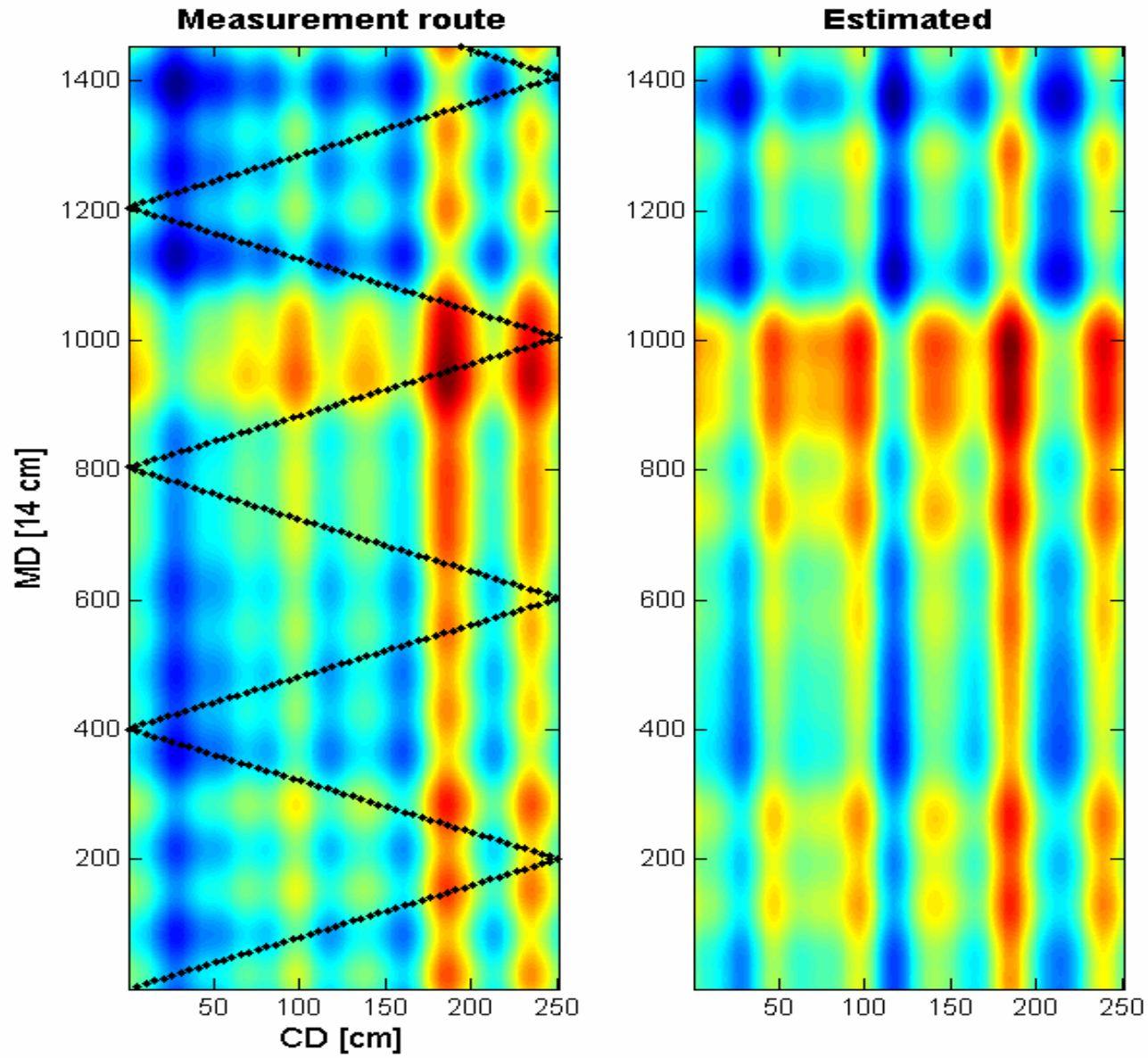
Measurement data --> math stuff ----> Voilà!

# The Kalman filter

- State vector  $x = [C_{cd1}, C_{cd2}, \dots, C_{md1}, \dots]$ 
  - Strongest Fourier components corresponding to CD and MD
- State vector update:  $x_{k+1} = x_k + K[y_i - Hx_k]$ 
  - $y_i$  = measurement data
  - $K$  = Kalman gain vector
  - $H$  = Inverse DFT operator
  - $y_i - Hx$  = difference between the model and a measurement



# Results 1



# Results 2

